# From Platonic solids to quivers

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#### **Abstract**

This course will be a whirlwind tour through representation theory, a major branch of modern algebra. We being by considering the symmetry groups of the Platonic solids, which leads naturally to the notion of a re ection group and its associated root system. The classi cation of these re ection groups gives us our rst examples of quivers (= direct graphs). Though easy to de ne, we'll see that the representation theory associated to quivers is very rich. We will use quivers to illustrate the key concepts, ideas and problems that appear throughout representation theory. Coming full circle, the course will culminate with the beautiful theorem by Gabriel, classifying the quivers of nite type in terms of the root systems of re ection groups. The ultimate goal of the course is to give students a glimpse of the beauty and unity of this eld of research, which is today very active in the U.K.

Exercises: The Platonic solids

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# Exercises: Re ection groups and root systems

1. Let 
$$E = x = x_i \cdot 2 \cdot 2 \cdot x_i \cdot 2 \cdot x_i = 0 ;$$
 where  $f$ ;

- (c) Let  $; 2 \mathbb{R}^n$ . Show that s s is a rotation of  $\mathbb{R}^n$ . Hint: decompose  $\mathbb{R}^n = \mathbb{R}f ; g$   $H \setminus H$  and consider s s acting on  $\mathbb{R}f ; g$ . If  $e_1; e_2$  is an orthonormal basis of  $\mathbb{R}^2$ , write out s and s explicit.
- 4. The *hypercube*  $H_n$  is the *n*-dimensional analogue of the square (n = 2), or cube (n = 3). Concretely, we can realize  $H_n$  in  $\mathbb{R}^n$  as the set of points

$$H_n = fv \ 2 R^n j \quad 1 \quad v_i \quad 1 \ i = 1; :::; ng:$$

The group of symmetries of  $H_n$  is denoted  $BC_n$ . It is called the *hyperoctahedral group*.

- (i) How many vertices does the  $H_n$  have? How about edges, or faces?
- (ii) The (n-1)-dimensional faces of  $H_n$  are the copies  $F_i$  of  $H_{n-1}$  given by  $fv \ 2 \ H_n \ j \ v_i = 1g$ . Since  $BC_n$  permutes these (n-1)-dimensional faces, it will permute their midpoints  $fe_i \ j \ i = 1; ::: ; ng$ , where

$$e_i = (0; :::; 0; 1; 0; :::; 0):$$

Deduce that w is a sign permutation matrix i.e. a matrix where each row has only one non-zero entry which is either a 1 or w1, and similarly for the columns.

- (iii) What is the order of the group  $BC_n$ ?
- (iv) The hyperoctahedron is dual to the hypercube. It is de ned to be

$$O_n = fx \ 2 \ \mathbb{R}^n \ j \ (x; v)$$
 1 for all vertices  $v$  of  $H_n g$ :

Check for n=2 and n=3 that one gets the (rotated by  $\frac{1}{4}$ ) square and octahedron respectively.

- (v) Show directly from the definition that the symmetries of  $H_n$  are also symmetries of  $O_n$ . This shows that  $W(H_n) = W(O_n)$ .
- (vi) Notice that the  $e_i$  are the vertices of  $O_n$ . Deduce that  $W(O_n) = BC_n$ .

### **Exercises: Quivers**

1. A homomorphism between representations. Let  $M = f(\mathbb{C}^{v_i}; ')g$  and  $N = f(\mathbb{C}^{w_i}; )g$  be representations of a quiver Q. Then a homomorphism  $\mathbf{f} : M \mid N$  is a collection of linear maps  $f_i \ge \operatorname{Hom}_{\mathbb{C}}(\mathbb{C}^{v_i}; \mathbb{C}^{w_i})$  for each  $i \ge Q_0$  such that the diagrams

$$\begin{array}{ccc}
 & C^{V_{t(\cdot)}} & \xrightarrow{\cdot} & C^{V_{h(\cdot)}} \\
 & \downarrow f_{t(\cdot)} & & \downarrow f_{h(\cdot)} \\
 & C^{W_{t(\cdot)}} & \longrightarrow & C^{W_{h(\cdot)}}
\end{array}$$

commute for all  $Q = Q_1$ . The space of all homomorphisms from M to N is denoted  $Hom_{\mathcal{O}}(M;N)$ .

(a) Consider the representations

$$M:$$
  $C^2 \xrightarrow{(a:b)} C$   $N:$   $C \xrightarrow{x} C$ 

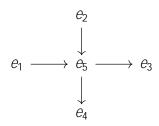
where  $a;b;c;d;x;y \in \mathbb{C}$ . If (a;b)=(2;1), (c;d)=(6;3), x=1 and y=3, construct a non-zero homomorphism  $\mathbf{f}:M \neq N$ . Are there any homomorphisms  $\mathbf{f}:M \neq N$  when (a;b)=(2;2), (c;d)=(6;4), x=2 and y=2? In general, what conditions do a;b;c;d;x and y need to satisfy for  $\operatorname{Hom}_{\mathcal{Q}}(M;N)$  to be non-zero? What is the dimension of  $\operatorname{Hom}_{\mathcal{Q}}(M;N)$  in this case?

(b) Recall that the representations of the quiver  $\stackrel{\longleftarrow}{e_1}$  are simply pairs (C<sup>n</sup>; A),

where  $A : \mathbb{C}^n / \mathbb{C}^n$  is an n matrix. If  $M = (\mathbb{C}^n / A)$ , show that  $\text{Hom}_{\mathcal{Q}}(M / M) = fB : \mathbb{C}^n / \mathbb{C}^n / [A / B] = 0g$ , where [A / B] := AB BA is the commutator of A and B.

- 2. Let Q be a quiver. Recall that, for each  $i 2 Q_0$ , we have defined the representation E(i) of Q.
  - (a) Show that the representation E(i) is simple.
  - (b) If Q has no oriented cycles, show that every simple representation equals E(i) for some  $i \ge Q_0$ .

- (c) Consider the quiver  $e_1$   $e_2$ . Show that the representation C  $e_2$   $e_3$   $e_4$  is simple.
- 3. Let Q be the quiver



Write down the basis of paths for the path algebra  $\mathbb{C}Q$ . What is dim  $\mathbb{C}Q$ ?

4. Let Q be the quiver  $e_1 \longrightarrow e_2 \longrightarrow e_3$  and let

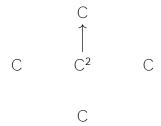
be the algebra of upper triangular 3  $\,$  3 matrices, where multiplication is just the usual matrix multiplication. Construct an explicit isomorphism of algebras  $\mathbb{C}Q$  / A.

## Exercises: Gabriel's Theorem

- 1. You'll notice that the positive de nite Euler graphs are precisely the positive de nite Coxeter graphs that are *simply laced* i.e. have at most one edge between any two vertices. Let  $(; )_C$ , resp.  $(; )_E$ , be the Coxeter form, resp. the Euler form, associated to a graph.
  - (a) Show that if is simply laced then ( ; ) $_E=2($  ; ) $_C.$
  - (b) If is not simply laced, show that there is no 2R such that  $(;)_E = (;)_C$ .
  - (c) Show that the symmetric matrix

corresponding to the Euler graph  $\bullet$  is positive definite if and only if m=1. When is it positive semi-definite?

- (d) By considering the subgraphs  $\bullet$  with m > 1 of , show that a non-simply laced Euler graph is not positive de nite.
- (e) Deduce Theorem 4.8 from Theorem 2.18.
- 2. Let  $i \supseteq Q_0$  be a sink. Show that  $S_i^+(E(i)) = 0$ .
- 3. Consider the representation  ${\it M}$  given by



which, under the identication  $e_i \ \mathcal{V}_{i} = i_{i+1}$ , corresponds to

$$R^+ = fe_1; e_2; e_3; e_1 + e_2; e_2 + e_3; e_1 + e_2 + e_3g;$$

For each of the above dimension vectors construct an explicit indecomposable representation of Q.